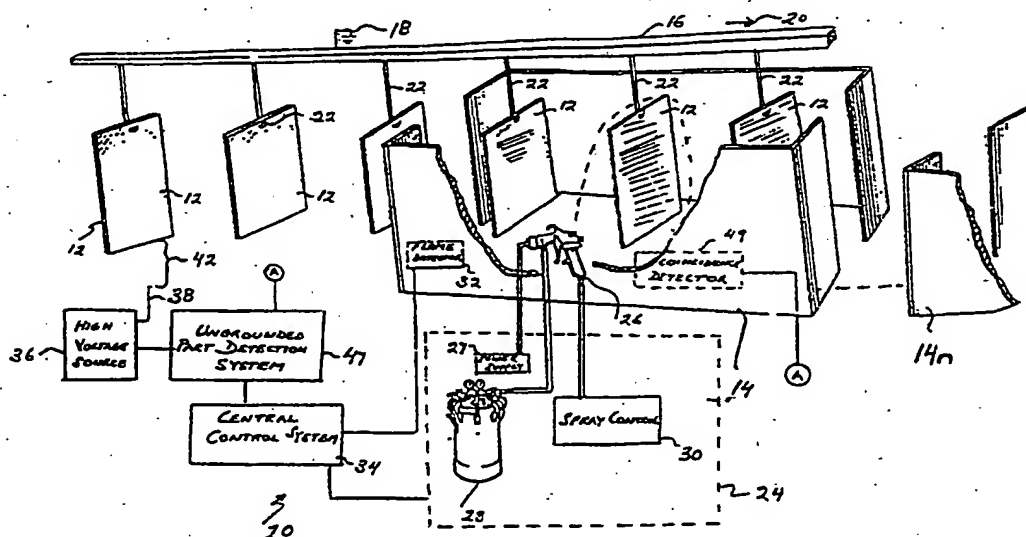




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(54) Title: SYSTEM AND PROCESS FOR COINCIDENCE DETECTION OF UNGROUNDED PARTS WITH DETECTORS LOCATED WITHIN AND OUTSIDE A PRODUCTION COATING AREA



(57) Abstract

A system (10) and a process for detecting and controlling ungrounded or inadequately grounded parts (12) prior to subjecting said parts (12) to an electrostatic coating process comprising: a radio-frequency detection system (47) located outside the electrostatic coating area for sensing energy levels radiated by sparking and/or corona discharge resulting from an ungrounded or inadequately grounded part (12) under test; and a coincidence detector (49) located within the electrostatic coating area for sensing and discriminating energy levels radiated by spurious sparking and/or corona discharge resulting from an external source other than said ungrounded or inadequately grounded part (12) under test.

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SYSTEM AND PROCESS FOR COINCIDENCE DETECTION OF UNGROUNDED PARTS WITH
DETECTORS LOCATED WITHIN AND OUTSIDE A PRODUCTION COATING AREA.

5

FIELD OF THE INVENTION

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This invention relates generally to the field of electrostatic coating of parts in a production line, for example, electrostatic painting (liquid and powder). More specifically, this invention relates to the field of detecting and controlling ungrounded parts during the electrostatic coating process by utilizing a coincidence technique.

15

Detecting ungrounded parts improves production flow, provides an overall cost savings by facilitating efficient use of the coating material, and prevents accidental fires and undesirable hindrances during production, for example, false shutdown.

BACKGROUND OF THE INVENTION

20

For many years, electrostatic coating or spraying has been a widely accepted technique for large scale application of paint, as for example, in a production painting line.

25

Typically, spraying involves the movement of very small droplets of "liquid" paint or particles of "powdered" paint from a nozzle to the surface of a part to be coated. The droplet or particle size may vary from less than 0.001 inches (0.025mm) to greater than 0.1 inches (2.54 mm) depending on the paint viscosity and the air pressure. When the droplets fall on the surface of the part, they flow together to form a

continuous wet coat.

Most industrial operations use conventional air spray systems in which compressed air is supplied to a spray gun and to a paint container. At the gun, the compressed air mixes, somewhat violently, with the paint, causing it to break up into small droplets, which are propelled toward the surface of the part to be coated. The process of breaking up the paint into droplets is referred to as "atomization."

Electrostatic spraying involves the movement of electrically charged paint droplets along lines of force that exist between an electrically charged spray gun and a grounded part. Because the paint follows electrical lines of force, it has less of a tendency to miss the part, thus reducing overspray. The paint generally "wraps around" to the rear surface of the part.

Atomization of the paint may be achieved by well-known air, airless, or rotational techniques. Air and airless electrostatic guns generally utilize an external ionizing electrode to ionize or charge the air surrounding the part to be coated. Alternatively, electrostatic guns also utilize a metal electrode located within the interior or at the paint container to charge the liquid paint before it is atomized. Rotational methods utilize a rotating electrically charged disk, bell, or cone to break up the paint. Atomization is achieved by a combination of centrifugal and electrostatic force.

There are many advantages to electrically coating parts in a production line. For example, electrostatically applied powder paint is often uniform in thickness, for the simple reason that the charged paint seeks the thinnest part of the film so it can better render its charge and adhere to the surface of the part. Smooth application on the edges of a part results from the wrap-around effect of the electrical field. In addition, electrostatic coating of parts in a production paint line facilitates efficiency.

In spite of the many production advantages, there exist safety concerns such as possibilities for electrical shock and fire hazards. A shock may be experienced if a person contacts any part of the coating system upon which energy is capacitively stored. The fire hazard is generally more severe. Sparks generally occur during the electrostatic coating operation. During electrostatic coating it is common to operate a device for dispersing and charging the coating material at a potential of 40,000 volts or higher. In instances, where the coating material is a paint in the form of a powder or has a volatile solvent, the danger of an explosion or fire from sparking is in fact quite serious.

Fires are also a possibility if electrical arcs occur between charged objects and a grounded conductor in the vicinity of an ignitable atmosphere. In any ungrounded metal object which acquires a charge because of its proximity to the gun, if the charge builds to a high enough level, an arc may

appear. The usual way to prevent the discharge-arc-fire problem is to ground every object in the paint booth.

For example, in a conventional coating system, parts to be coated are generally transported through a coating zone by a mechanical conveyor. The conveyor is operated at ground potential and the parts are supported on the conveyor by hooks or supports of conductive material to also maintain the parts at ground potential. The coating device includes an electrically charged electrode, preferably at a negative potential with respect to ground. A bad contact between the metallic part to be coated and the conveyor, which can result from a conveyor hook being partly covered with paint, corrosion, grease, phosphate, or powder during previous passages through the coating zone, can exist. In general, conveyor hooks are not sufficiently cleaned after passing through the coating zone, so that after a number of successive passages, they are covered with a crust which is sufficiently insulating to prevent electric contact between the metallic part to be coated and the grounded conveyor. In consequence, the part to be coated, as it passes close to the electrodes under high tension, acquires electric charges, which accumulate on the part until it develops a potential sufficiently high to cause the breakdown of the insulating crust between the part and the hook. This poses a two-fold problem. First, the breakdown is accompanied by a spark capable of developing sufficient energy to ignite the surrounding mixture of air and

finely divided coating product particulates and/or vapor. In addition, many of the benefits associated with electrostatic coating are lost if the articles are not properly grounded to terminate the electrostatic field.

5 To maintain the efficiency of the electrostatic coating process, the spray head and the supporting surfaces must be frequently cleaned. If these surfaces become coated with a layer of dirt or grime, the electrical charge may eventually leak through this layer and be grounded. This typically
10 reduces the charging efficiency of the spray gun as well as decreases attraction to the spray gun. Moreover, the wrap-around effect is reduced and overspray is increased. Frequent cleaning, although necessary, is undesirable in view of the manual labor it involves, which hinders the automated process.

15 U.S. Patent No. Re. 28,394 to Point proposes an apparatus for testing electrical contact between metallic objects. However, the apparatus proposed in that patent merely detects sparks with the intention of preventing fires. In addition, U.S. Patent No. 3,787,707 to Gregg also proposes a spark
20 detector apparatus and method to distinguish disruptive charges in the electrostatic system from a corona discharge or random sparking of other electrical equipment by detecting the presence of repetitive charges.

In general, with prior detector systems, troublesome false
25 alarms have unnecessarily caused deliberate disconnection or disarming of those systems. The false alarms may be caused by

welding, lightening, sparking commutators, plating units etc.

Thus, a system and method for detecting and controlling ungrounded parts in a production line is desirable.

SUMMARY OF THE INVENTION

5 The present invention is directed to a system and method for detecting ungrounded parts during the electrostatic coating process in order to improve production flow, provide an overall cost savings by facilitating efficient use of the coating material, and prevent accidental fires and undesirable
10 hindrances during production, for example, false shutdown.

 The system of the present invention comprises a detection system for detecting any ungrounded parts prior to those parts entering the coating zone, such as a painting booth. The detection system in accordance with one embodiment utilizes a
15 coincidence detection technique, which performs a test for radio-frequency electromagnetic energy radiated by sparking and/or corona discharge caused by ungrounded parts outside the painting booth and a test for isolating radio-frequency electromagnetic energy radiated by sparking and/or corona
20 discharge caused by any other means inside the painting booth. In accordance with an alternative embodiment, the test performed outside the booth may include a further test for detecting ultraviolet energy radiated by the sparking and/or corona discharge. Upon detecting an ungrounded part, the part
25 may be removed from the production line and appropriate steps to properly ground it may be taken, for example, the hook maybe

cleaned or the like. Performing coincident tests thus prevents false shutdowns in the production line.

The detection system may comprise a radio-frequency (RF) wave sensor associated with a first antenna and an ultraviolet sensor located outside the painting booth, which generate
5 representative signal waveforms providing an indication of the energy radiated by the sparking and corona discharge caused by an ungrounded part. A second antenna associated with the radio-frequency (RF) wave sensor is located within the painting
10 booth to sense radio-frequency energy radiated by other sources. Upon sensing an actual ungrounded part, select circuits are activated to actuate an appropriate one of several functions, such as an alert, a system fault and the like, connected in parallel.

15 These as well as other features of the invention will be apparent to one skilled in the art from the following detailed description of some specific embodiments thereof.

BRIEF DESCRIPTION OF THE DRAWING FIGURES

Further features and advantages of the invention will
20 become readily apparent from the following specification and from the drawings, in which:

Figure 1 is a diagrammatic illustration of an electrostatic coating system and process in accordance with the present invention, in which parts are moved by a conveyor
25 through a coating zone showing a detection system in accordance with the present invention for checking ungrounded parts in the

production paint line;

Figure 2 is a block diagram of the detection system of Figure 1 wherein sparking or corona discharge induced by a high voltage is observed; and

5 Figure 3 is a cross sectional view of an exemplary part under test, illustrating application of a high voltage and the resistive air gap between the high voltage source and the exemplary part.

DETAILED DESCRIPTION OF SOME PREFERRED EMBODIMENTS

10 Figure 1 illustrates an exemplary system 10 in accordance with the present invention for detecting and controlling the presence of any ungrounded parts or articles prior to electrostatic coating of the parts in a production coating line, for example, an electrostatic painting (liquid or powder)
15 line. With reference to Figure 1, preliminarily, the general environment with respect to electrostatic coating along with some aspects of the operation is described.

As illustrated in Figure 1, parts 12 are transported through a coating zone, such as a painting or spraying booth or
20 enclosure 14, by a conveyor 16 connected to a reference potential or ground indicated at 18. A plurality of spraying booths 14-14n are shown in Figure 1. It should be recognized that the detection system discussed in this application with respect to spraying booth 14 may be installed in one or more
25 spraying booths as desired. The direction in which the conveyor 16 moves is indicated by an arrow referenced as 20.

The parts 12 are typically supported from the conveyor by a conductive hook-like support or hanger 22.

The electrostatic coating system illustrated in Figure 1 represents an air electrostatic spray system of a type used in many industrial operations. A typical industrial spray system indicated at 24 includes a spray gun 26 coupled to a power supply 27, a paint supply container 28 (for example, a pressure tank) and some form of spray control mechanism indicated by block 30. The spray control mechanism 30 may include an air compressor and an air regulator (not separately shown).

Conventional air spray guns may be of the pressure or suction feed type. Pressure-feed guns are usually used where large volumes of paint must be applied rapidly. Such air spray guns use paint supplied by air or mechanical pressure.

Suction-feed guns are used where a number of colors are required on an intermittent basis for low volume production, such as in automobile refinishing. The paint is supplied from a cup connected directly to the spray gun by creating a vacuum over the paint and allowing it to rise to the air cap of the gun through a feed tube, which extends down into the paint cup. The vacuum occurs when compressed air from the air cup rushes over the gun orifice and aspirates air from within the feed tube. The paint flows from within the cup to replace the aspirated air and is atomized by the pressurized air at the gun tip. Air, pressure-feed spray guns are well known and used in many industrial operations.

The air spray gun 26 is mounted at a predetermined distance from the surface of the part 12 facing the air spray gun 26. The distance affects both the film thickness and appearance. Spray gun manufacturers generally recommend that the spray gun 26 should be mounted at a distance of about 12 inches. Many automatic spray set-ups move the spray head away from and toward the part 12, in the event its shape changes so that a constant distance is maintained.

The paint supply container 28 generally holds the paint under an air pressure sufficiently high to force the paint to the spray gun 26 at a desired rate. Delivery rates of 420-720 ml per minute are typical and the size of such containers vary depending on applications. For example, a single container may supply several spray guns. For larger operations, paint is often supplied from drums with a capacity of 55 or more gallons. Some large industrial installations may circulate pressurized paint from a central mix room to ten or more spraying booths. When drums or large tanks are used, the paint may be supplied by air or hydraulically driven pumps rather than by direct air pressure. Thus, the system illustrated in Figure 1 is intended to represent any one or more of the above described situations.

An exemplary spray control mechanism 30 may comprise a conventional air compressor and air regulator. In a conventional air compressor, an electrically driven piston usually keeps the pressure in an air tank within a pre-set

range. Air from this tank is supplied to the paint tank 28 and the spray gun 26. The air regulator (shown as part of the spray control block) allows air at different pressures to be supplied to the paint container and the spray gun. The regulator often includes a filter to trap air and water which may be present in the line.

Alternatively, airless spraying techniques may also be used. Unlike air spray systems, airless guns use no air at all. Paint is supplied to the gun at very high pressures, typically 1000-4000 psi. When the pressurized paint enters the much lower pressure region in front of the spray gun, the sudden drop in pressure causes the paint to be atomized. This process is similar to water being emitted from a garden hose.

The spraying booths 14-14n are enclosures around the painting area configured to keep paint within the paint area and the dirt out of the wet paint. Spraying booths 14-14n may be of the downdraft or sidedraft variety typically used in most industrial operations. Downdraft booths are generally used for large parts to facilitate painting from two sides to avoid the need for turning the parts. Sidedraft booths are generally used for smaller parts sprayed from one side only. Most spraying booths have a volume of water which traps the excess (overspray) paint. Chemicals in the water coagulate the paint. However, some production paint booths are operated dry, that is, with disposable filters rather than water to trap excess paint.

Spraying booths 14-14n may have flame detectors 32 disposed at appropriate locations to provide an indication of fire to a central control system indicated at 34.

Prior to entering the spraying booth 14-14n, the parts 12 to be coated are tested to assure that they are adequately grounded. The parts 12 are passed proximate a high voltage source 36 with a high voltage antenna 38. The high voltage source 36 may be one available from Nordson Corporation as EPU-9. Electrical charge is transferred from the high voltage source, which may operate between 60,000-120,000 volts, to the parts 12 to be coated, through a resistive air gap (shown more clearly in Figure 3), indicated at 42. A detection system 47 (in Figure 1, shown located outside the spraying booth 14) detects the level, if any, of ultraviolet or radio-frequency energy or both, radiated by sparking and corona discharge caused by an ungrounded part. As shown in Figure 2, in some cases the detection system may be located within the spraying booth 14, as indicated by 47'.

The detection system 47 or 47' may be located at a fixed position proximate the conveyor 16 or, alternatively, the detection system 47 or 47' may be moved or scanned over the production line of parts 12. The parts 12 within the painting booth 14 are distinguished with shading lines to indicate painted surfaces. A coincidence detector 49 may be located inside the spraying booth 14 to sense radio-frequency energy radiated by other sources. Alternatively, in the event the

detection system 47' is located within the spraying booth 14, the coincidence detector may be located outside the spraying booth 14, as indicated by 49' (Figure 2). The coincidence detector 49 upon sensing such energy relays it to detection system 47 as indicated by the coupler "A."

Referring now to Figure 2, in accordance with one embodiment of the present invention, the detection system 47 may comprise a UV (ultraviolet) sensor 50 for sensing ultraviolet light and a RF (radio-frequency) sensor 52 with an associated first antenna 53 for sensing radio-frequency electromagnetic waves to provide an indication of sparking and/or corona discharge.

The RF sensor 52 utilizes well-known techniques for sensing radio-frequency electromagnetic energy and generates a representative signal indicating the amount of energy sensed. In accordance with a preferred embodiment, the RF sensor 52 utilizes a first antenna 53 located outside the painting booth 14 to sense the amount of energy radiated by a sparking and/or corona discharge and a second antenna 57 (within the coincidence detector 49) to discriminate spurious radio-frequency energy radiated by other external sources, such as lightning. In accordance with an alternative embodiment, the UV sensor 50 may be utilized to provide an indication of the ultraviolet energy radiated by the sparking and/or corona discharge. Both the RF sensor 52 and the UV sensor 50 utilize well known techniques for sensing radio-frequency and

ultraviolet energy. The UV sensor 50 is responsive to UV radiation within a spectral band selected to include UV radiation typically emitted with sparking and or corona discharge and generates a signal indicative of the sensed radiation.

The output signals representing the sensed radiation from the RF sensor 52 and the UV sensor 50, which may be digitally processed, are indicated by lead lines 60 and 58, respectively.

Upon confirmation that the spark or corona discharge is caused by an ungrounded part, information data is relayed to the central control system 34 as indicated by data bus 70. Select circuits (shown as part of the central control system) within the central control system 34 associated with select functions, such as an alert 72, a fire alarm 74, a system fault indicator 76, an ungrounded part indicator 78, and the like may be selectively activated to actuate an appropriate one of the select functions. The central control system 34 may also include conventional interface ports, such as an RS-232 port, indicated at 80, and an RS-485 port, indicated at 82. For example, when a part is found to be ungrounded, the central control system 34 may actuate the ungrounded part indicator 78 or the alert 72 or both. Likewise, when flame is detected by the flame detector 32 (Figure 1), the central control system 34, may actuate the fire alarm 74. Upon detecting some system fault or error, the central control system may actuate the system fault indicator 76 to cause a shutdown of the production

line.

The central control system 34 has modem capabilities to facilitate communication by telephone (including cellular) to allow the present system 10 to be interrogated, serviced, and so on, from a remote location. In the disclosed embodiment the central control system 34 is coupled to one or more remote terminals illustrated at TN (Figure 2) through communication facility C. The communication facility C represents a telephone system for interconnecting any associated terminals.

Also, in some instances it may be advantageous to utilize more than one detection system for a single spraying booth, or alternatively, a single detection systems may be utilized with multiple coincidence detectors located in plural spraying booths.

While the invention has been described in conjunction with specific embodiments thereof, many alternatives, modifications and variations will be apparent to those skilled in the art in view of the foregoing description. Accordingly, it is intended to embrace all such alternatives, modifications and variations which fall within the spirit and scope of the appended claims.

What is claimed is:

1 1. A system (10) for detecting and controlling
2 ungrounded or inadequately grounded parts (12) prior to
3 subjecting said parts (12) to an electrostatic coating process
4 in an electrostatic coating area, comprising:

5 a source (36) for imparting an electrical charge to
6 said parts (12) under test;

7 a radio-frequency detection system (47) located
8 outside the electrostatic coating area for sensing energy
9 levels radiated by sparking and/or corona discharge
10 resulting from an ungrounded or inadequately grounded part
11 (12) under test; and

12 a coincidence detector (49) located within the
13 electrostatic coating area for sensing and discriminating
14 energy levels radiated by spurious sparking and/or corona
15 discharge resulting from an external source other than
16 said ungrounded or inadequately grounded part (12) under
17 test.

1 2. A system (10) for detecting and controlling
2 ungrounded or inadequately grounded parts according to claim 1,
3 wherein said detection system further comprises:

4 an ultraviolet sensor (50) for sensing energy levels
5 radiated by sparking and/or corona discharge resulting
6 from an ungrounded or inadequately grounded part (12)
7 under test.

1 3. A system (10) for detecting and controlling
2 ungrounded or inadequately grounded parts according to claim 1,
3 wherein said detection system (47) comprises a RF sensor (52)
4 with a first antenna (53) for sensing radio-frequency magnetic
5 energy radiated by sparking and/or corona discharge resulting
6 from an ungrounded or inadequately grounded part (12) under
7 test.

1 4. A system (10) for detecting and controlling
2 ungrounded parts (12) or inadequately grounded parts (12)
3 according to claim 1, wherein said coincidence detector (49)
4 comprises a second antenna (57) for sensing radio-frequency
5 magnetic energy radiated by sparking and/or corona discharge
6 resulting from said external source.

1 5. A system (10) for detecting and controlling
2 ungrounded parts or inadequately grounded parts according to
3 claim 1, further comprising:
4 a central control system (34) coupled to said radio-
5 frequency detection system (47) and said coincidence
6 detector (49) to receive data indicative of an ungrounded
7 or inadequately grounded part (12); and
8 a plurality of function indicators coupled to said
9 central control system (34) and selectively actuated by
10 said central control system (34) to indicate a specific

11 one of a plurality of conditions.

1 6. A system (10) for detecting and controlling
2 ungrounded or inadequately grounded parts according to claim 5,
3 further comprising:

4 a flame detector (32) located within the
5 electrostatic coating area said flame detector (32)
6 providing an indication of fire to said central control
7 system (34).

1 7. A process for detecting and controlling ungrounded or
2 inadequately grounded parts (12) prior to subjecting said parts
3 to an electrostatic coating process in an electrostatic coating
4 area, comprising the steps of:

5 imparting an electrical charge to said parts (12)
6 under test;

7 disposing a radio-frequency detector outside the
8 electrostatic coating area for sensing energy levels
9 radiated by sparking and/or corona discharge resulting
10 from an ungrounded or inadequately grounded part under
11 test; and

12 disposing a coincidence detector (49) within the
13 electrostatic coating area for sensing and discriminating
14 energy levels radiated by spurious sparking and/or corona
15 discharge resulting from an external source other than
16 said ungrounded or inadequately grounded part (12) under

17 test.

1 8. A process for detecting and controlling ungrounded or
2 inadequately grounded parts (12) according to claim 7, further
3 comprising the steps of:

4 sensing ultraviolet energy levels radiated by
5 sparking and/or corona discharge resulting from an
6 ungrounded or inadequately grounded part under test.

1 9. A process for detecting and controlling ungrounded or
2 inadequately grounded parts (12) according to claim 7, further
3 comprising the steps of:

4 transmitting data from said radio-frequency detector
5 and said coincidence detector (49) indicative of an
6 ungrounded or inadequately grounded part (12) to a central
7 control system (34); and

8 selectively actuating a plurality of function
9 indicators coupled to said central control system (34) to
10 indicate a specific one of a plurality of conditions.

1 10. A process for detecting and controlling ungrounded or
2 inadequately grounded parts (12) according to claim 9, further
3 comprising the steps of:

4 detecting fire within the electrostatic coating area
5 and providing an indication of the fire to said central
6 control system.

1/3

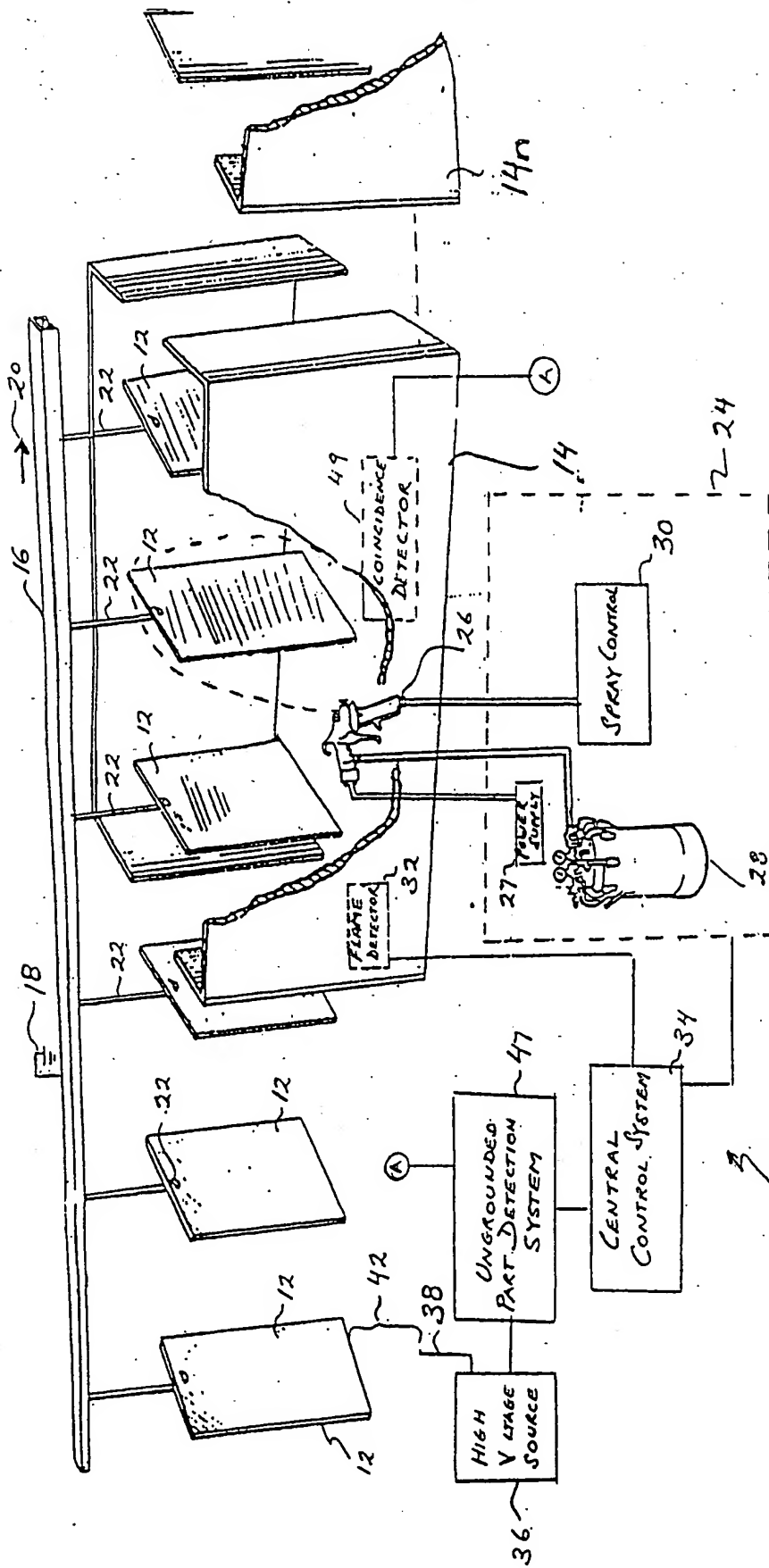
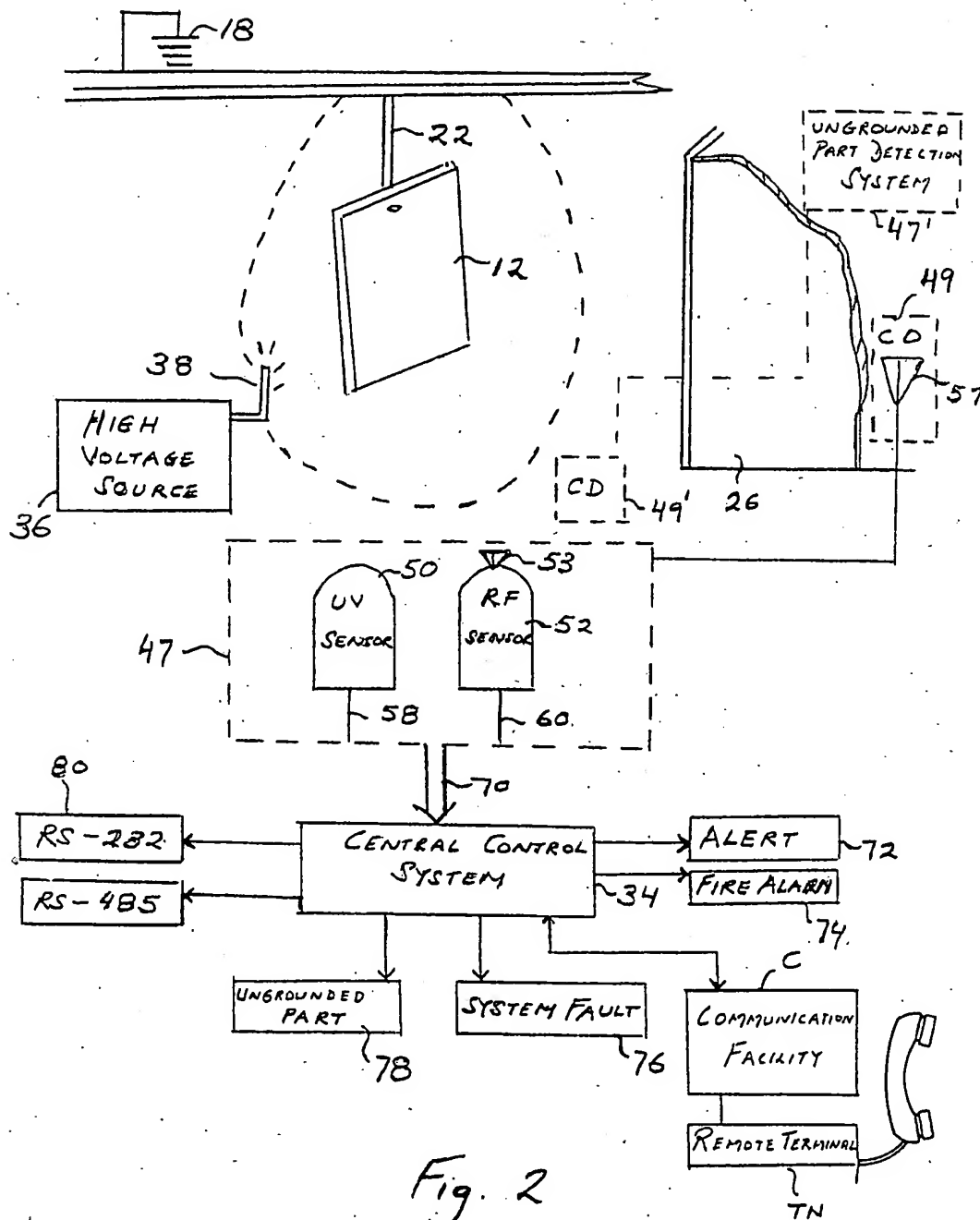


Fig. 1



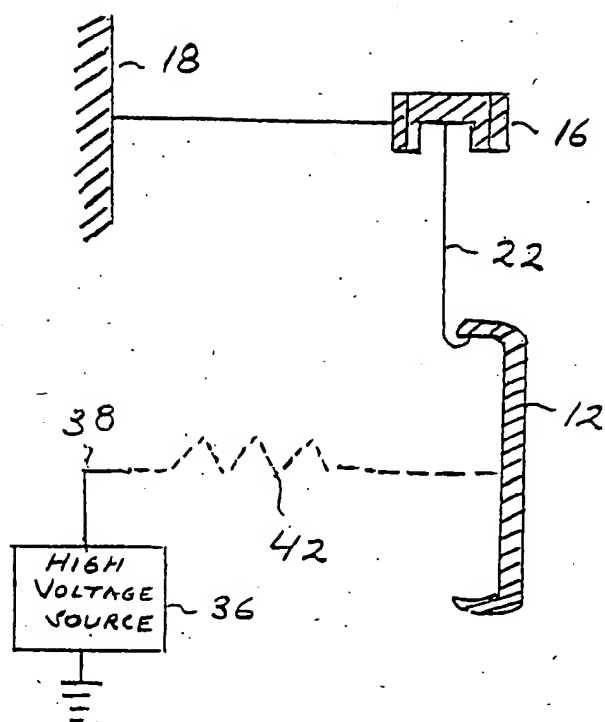


Fig. 3

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US 96/10754

A. CLASSIFICATION OF SUBJECT MATTER

IPC6: B05B 5/08, G01R 31/00, H02H 7/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC6: B05B, G01R, H02H

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

DIALOG WPI, CLAIMS, JAPIO

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US, A, 4586657 (GRAHAM C. JOHNSON ET AL), 6 May 1986 (06.05.86), column 3, line 23 - column 4, line 10, figure 4, claim 1 --	1,7
A	US, A, 3787707 (PAUL S. GREGG), 22 January 1974 (22.01.74), column 5, line 38 - column 6, line 40 --	1-10
A	US, E, 28394 (MARCEL POINT), 15 April 1975 (15.04.75), claim 1 -----	1-10

☐ Further documents are listed in the continuation of Box C.
 ☒ See patent family annex.

* Special categories of cited documents:

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Date of the actual completion of the international search

24 Sept 1996

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INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.

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Patent document cited in search report	Publication date	Patent family member(s)	Publication date
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